

# AWAIC: A WISE Astronomical Image Co-adder

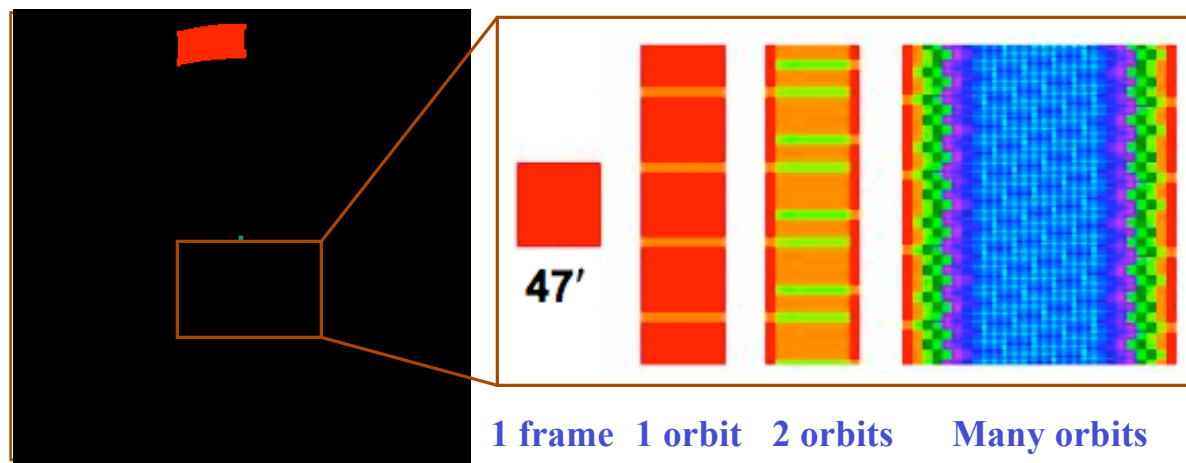
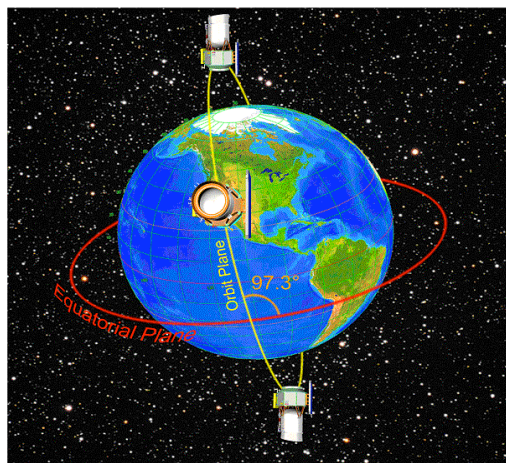
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# WISE: A Simple Mission Design



- The **W**ide-field **I**nfrared **S**urvey **E**xplorer: all-sky survey at 3.3, 4.7, 12 & 23  $\mu\text{m}$  with  $\sim 10^3 \times$  more sensitivity than previous surveys

- 523 km, circular, polar orbit
- One month of checkout
- 6 months of survey ops

- Scan mirror “freezes” orbital motion  $\Rightarrow$  efficient mapping
  - 8.8-s exposure per frame
  - 10% frame to frame overlap (in-scan)
  - 90% orbit to orbit overlap (cross-scan)

- Expect to achieve a median of 8 exposures/position on the ecliptic equator,  $> 1000$  exposures at poles
- Requirement is to have  $> 95\%$  of sky with  $\geq 4$  frame exposures
- Scheduled for launch at 6:00 am on November 1st 2009!



# WISE Products



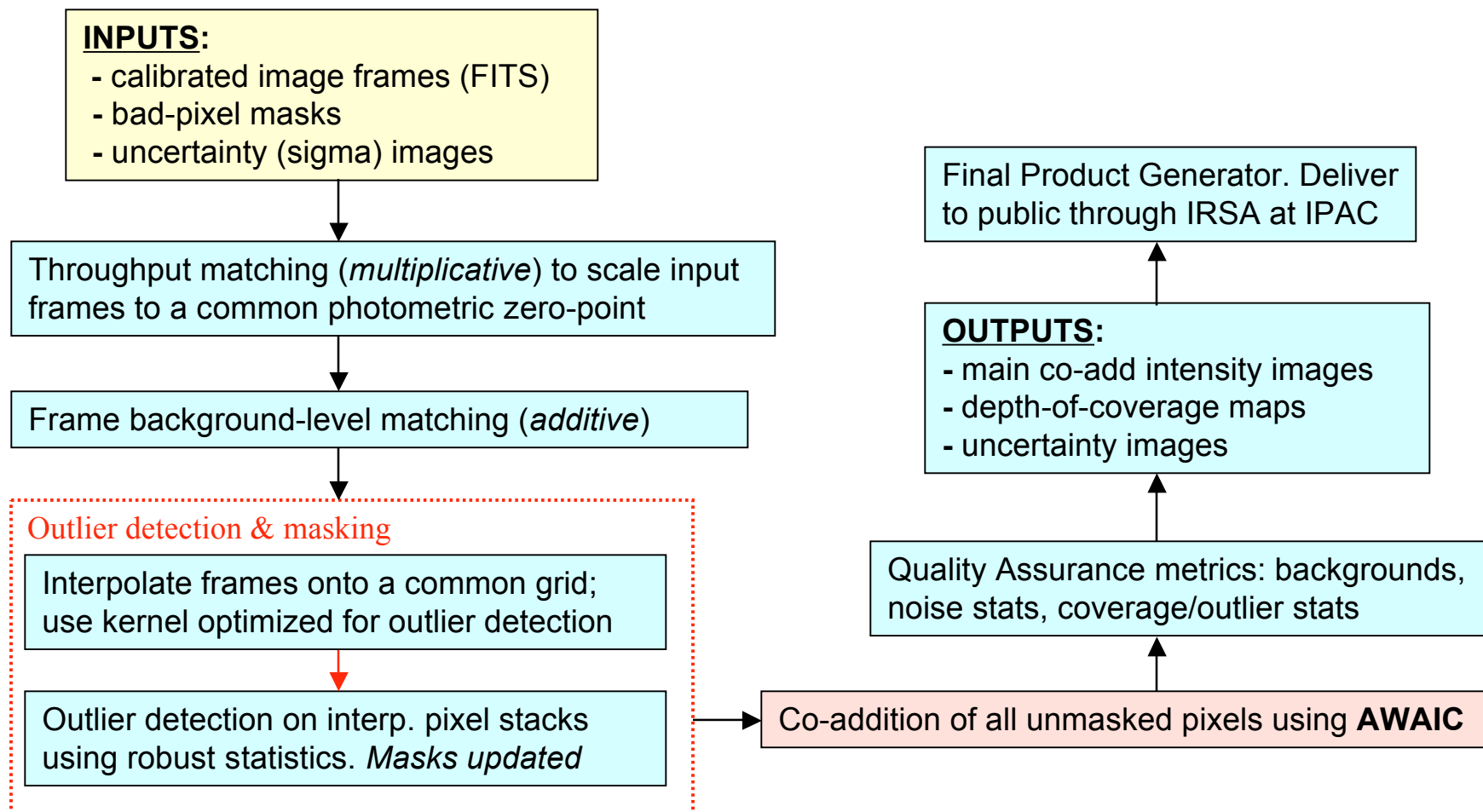
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WISE will deliver to the scientific community:

- A digital Image Atlas containing  $\sim 220,000$  co-adds of the survey frame exposures covering the whole sky in 4 mid-IR bands
- Ancillary co-add products: depth-of-coverage maps and uncertainty maps
- Atlas Image tiles are  $\approx 1.5^\circ \times 1.5^\circ$  re-sampled at  $1.375''/\text{pixel}$
- A Source Catalog of  $\approx 5 \times 10^8$  objects merged across all 4 bands to photometric  $S/N = 5$ . All sources will be astrometrically and photometrically calibrated



# Co-addition Pipeline Overview







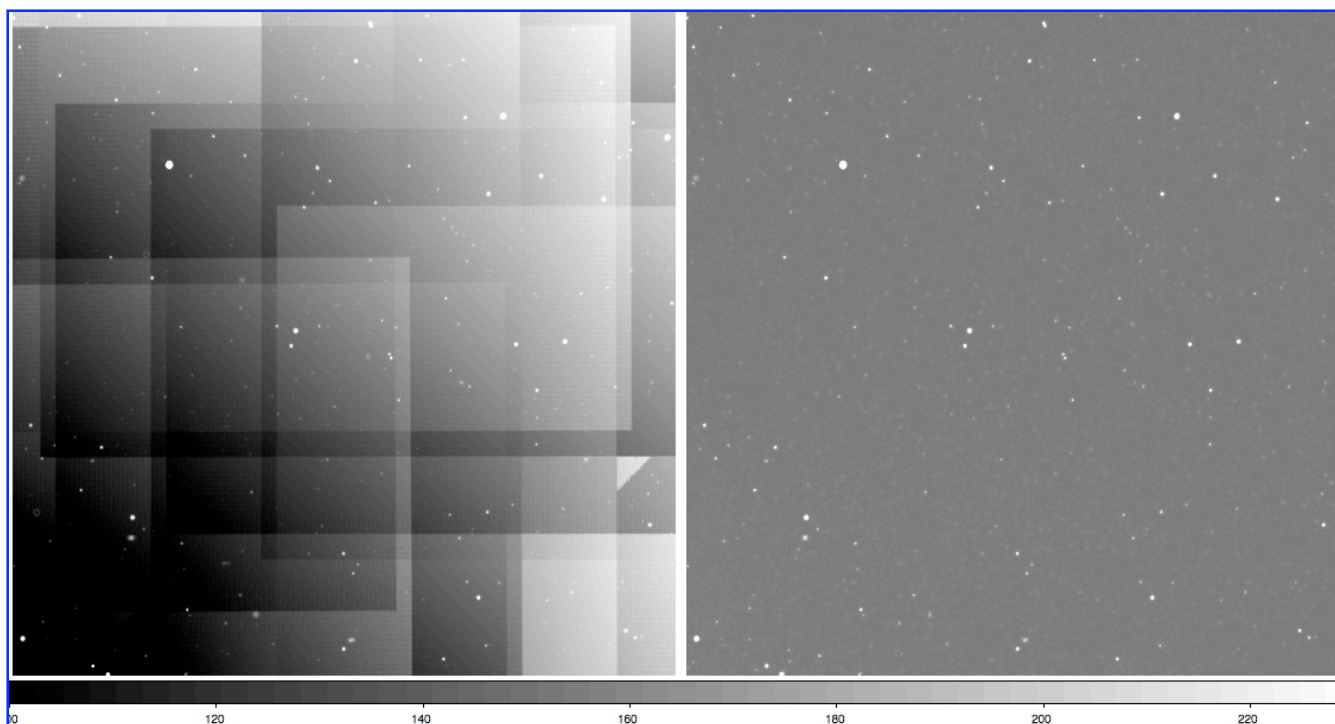
# Background-level Matching



- Instrumental transients lead to varying background levels between frames
- **Goal:** obtain seamless (or smooth) transitions between frames across overlaps
- **Simple method:** fit a “robust” plane to each frame, subtract to equalize frames, then add back a common plane or level to all frames computed from a median over all the fits

No matching

With matching

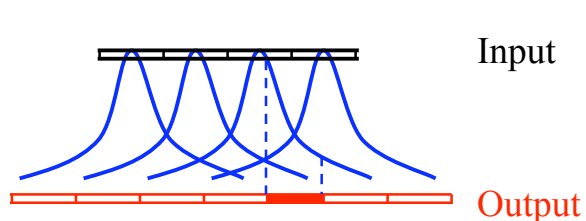




# Image Co-addition in AWAIC



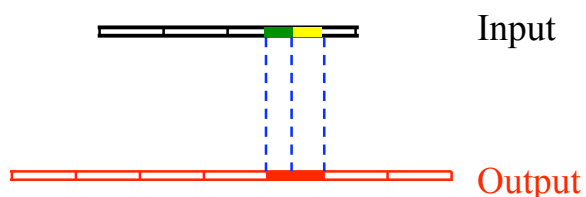
- **Goal:** want to optimally combine all measurements into a *faithful* representation of the sky
- AWAIC uses the detector's **P**oint **R**esponse **F**unction (PRF) as the interpolation kernel
- **PRF** = *P*oint *S*pread *F*unction (*PSF*)  $\otimes$  *p*ixel *r*esponse
  - each pixel collects light from its vicinity with an efficiency described by the PRF
- Flux in a co-add pixel  $j$  is estimated using PRF and inverse-variance weighted averaging:



$$f_j = \frac{\sum_i \frac{r_{ij}}{\sigma_i^2} D_i}{\sum_i \frac{r_{ij}}{\sigma_i^2}}$$

$\leftarrow$  Input detector (pixel) measurements  
 $\leftarrow$  PRF (volume normalized to unity)  
 $\leftarrow$  Variance from propagated noise model (optional)

- For comparison, the popular overlap-area weighted interpolation method (e.g., *Montage*, *MOPEX*, *drizzle*...):



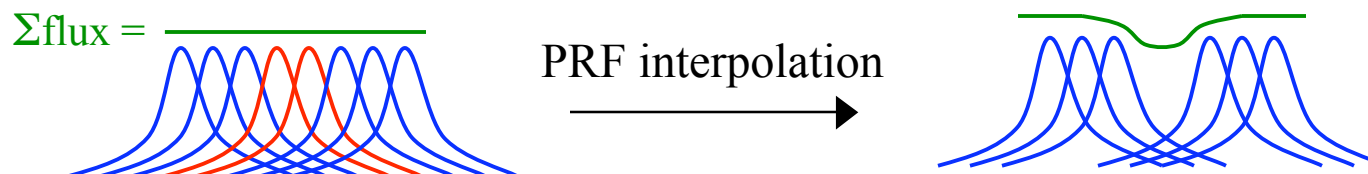
$$f_j = \frac{\sum_i \frac{a_{ij}}{\sigma_i^2} D_i}{\sum_i \frac{a_{ij}}{\sigma_i^2}}$$



# Why PRF as Interpolation Kernel?



- Reduces impact of masked pixels if the data are well sampled (even close to critical). Leads to effectively non-zero coverage at the bad pixel locations on co-add due to overlapping PRF tails:



- Defines a linear matched filter optimized for point source detection
  - High frequency noise is smoothed out without affecting point source signals  $\Rightarrow$  peak S/N maximized
  - Process is effectively a cross-correlation of a point source template (the PRF) with input data
  - This will benefit processing at the WSDC since a source catalog is one of its release products
- The big one: allows for resolution enhancement (HiRes): PRF can be “deconvolved” - more later
  - Not in WISE automated pipeline. Implemented to support offline research



## Other Features in AWAIC



- 
- Allows for a spatially varying PRF. Usually non-isoplanatic over the focal plane for large detector arrays
  - Ancillary products (for both simple co-addition and HiRes'ing):
    - Uncertainties in co-add pixel fluxes: from input prior model or *a posteriori* from repeatability
    - depth-of-coverage maps and images of outlier locations
    - Quality Assurance metrics on depth-of-coverage; sky-backgrounds; outliers;  $\chi^2$  tests to validate uncerts
  - Supports:
    - FITS standard;
    - WCS standards with distortion;
    - five commonly used projections: TAN, SIN, ZEA, STG, ARC implemented in a fast re-projection library
  - Generic enough for use on any astronomical image data: exercised extensively on *Spitzer* and *HST* data

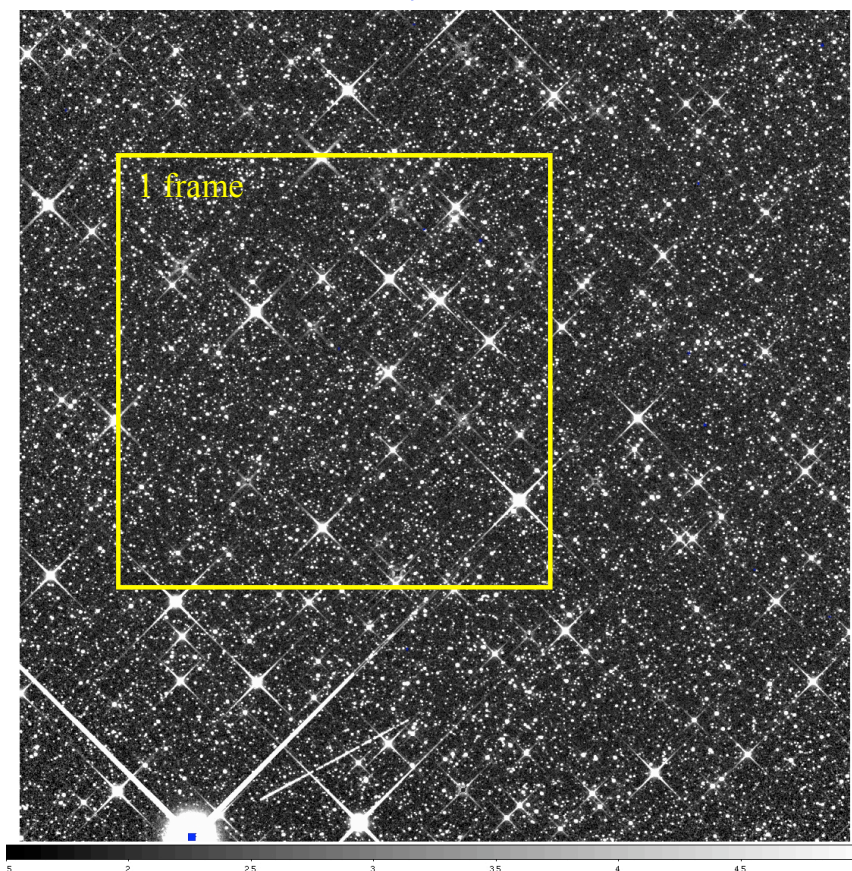


## Example of WISE Atlas Images



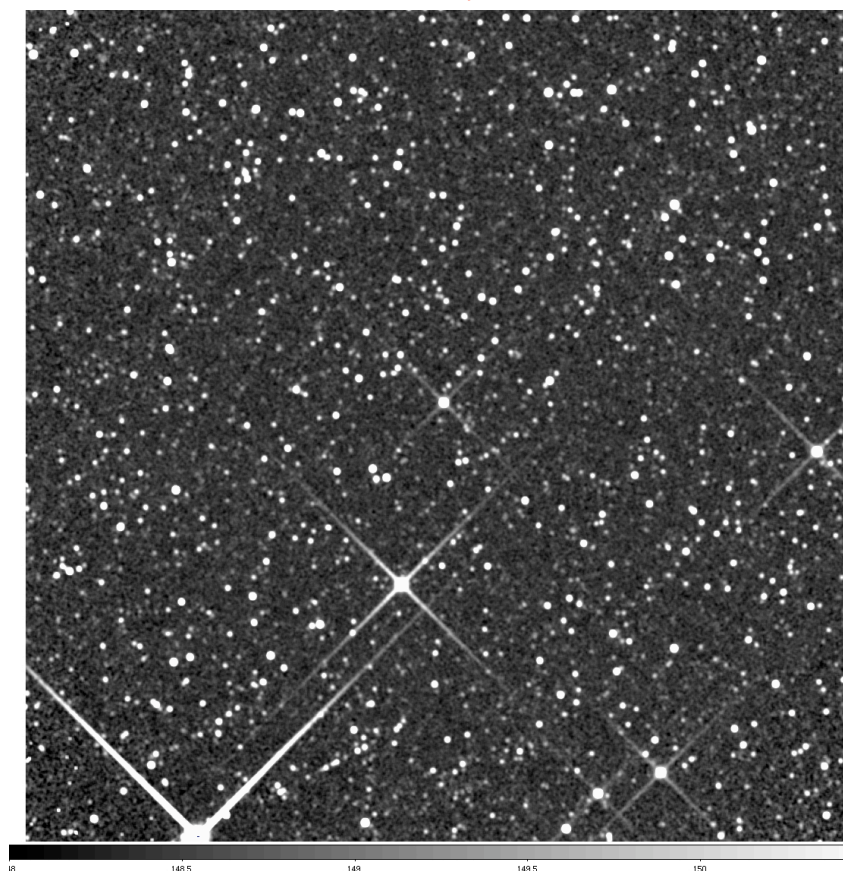
- Simulated frames provided by Ned Wright (P.I.): used seed sources from 2MASS catalog
- Mid-ecliptic latitude field ( $\beta \approx +30^\circ$ ) - example of what WISE *may* see

3.3  $\mu\text{m}$



1.56°

23  $\mu\text{m}$



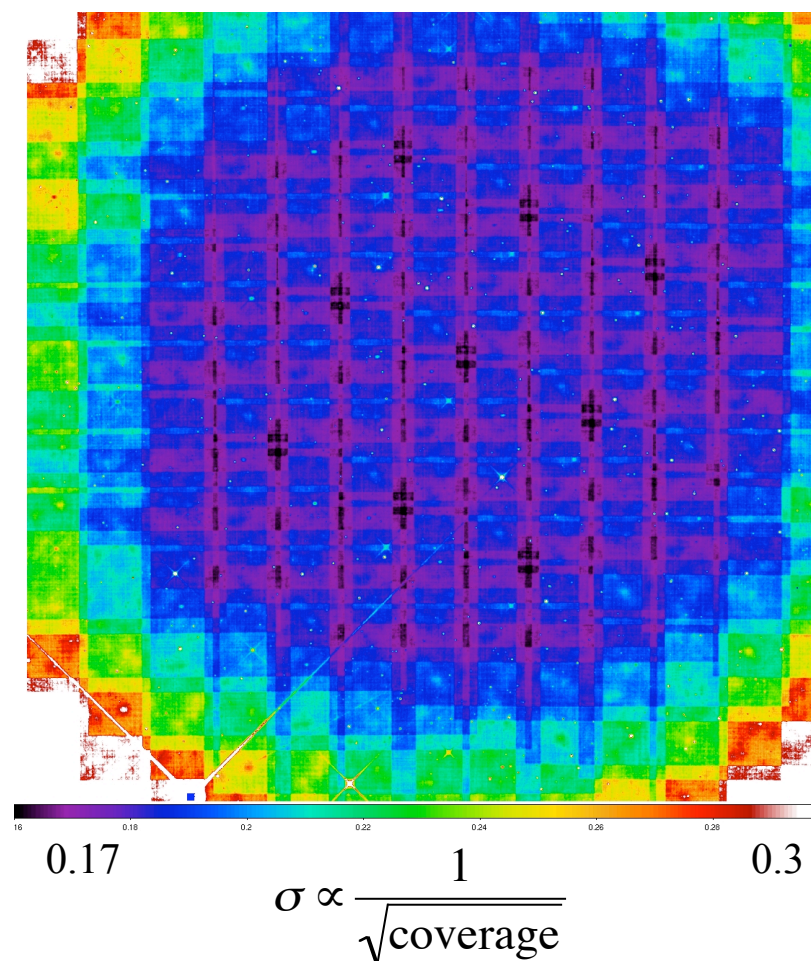
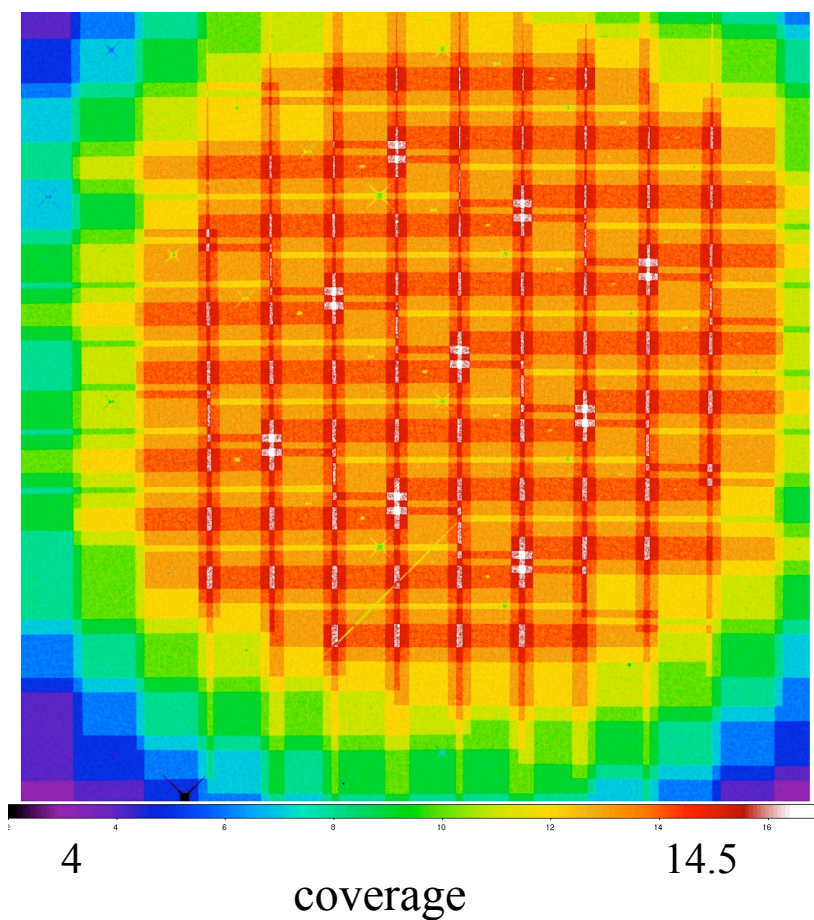




# Depth-of-coverage and $\sigma$ maps



- Depth-of-coverage map: effective number of repeats from all *unmasked* pixels at each location
- $\sigma$ -map: 1-sigma uncertainty for each pixel propagated from a noise model







## South Ecliptic Pole (near LMC)



### WISE “Touchstone field”

Combines AWAIC mosaics in  
*Spitzer* bands:

4.5μm (blue)

8μm (green)

24μm (red)

⇒ Proxy for WISE bands 2, 3, 4

~ 20' ~ 1/5 of WISE Atlas Image



# HiRes: Maximum Correlation Method (MCM)



- Originally implemented for IRAS ~ 22 years ago. Now extended and made more generic.
- Earlier we discussed combining images to create a co-add, **MCM** asks the reverse:
  - what model of the sky propagates through the measurement process to yield the observations within measurement error?
- Measurement process is a filtering operation performed by the instrument's Point Response Function (PRF):

$$\boxed{\text{Sky "truth" } \otimes \underbrace{PSF \otimes \Pi}_{PRF} \otimes \text{sampling} \rightarrow \text{measurements}}$$

- MCM starts with a “maximally correlated” image - a flat model image and modifies (or de-correlates) it to the extent necessary to make it reproduce the measurements. The model is iteratively refined.
- Includes:
  - a ringing suppression algorithm (minimize leakage of power into low-frequency side-lobes);
  - allows for spatially varying PRFs over focal plane;
  - uncertainty estimation;
  - diagnostic variance images for outliers and assessing convergence

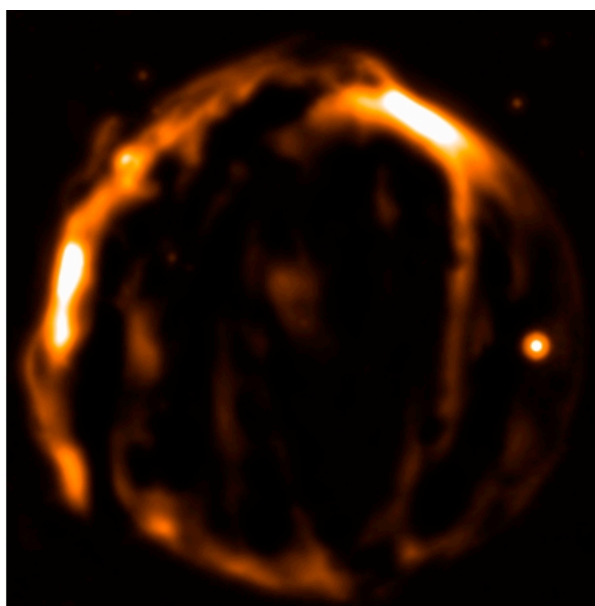




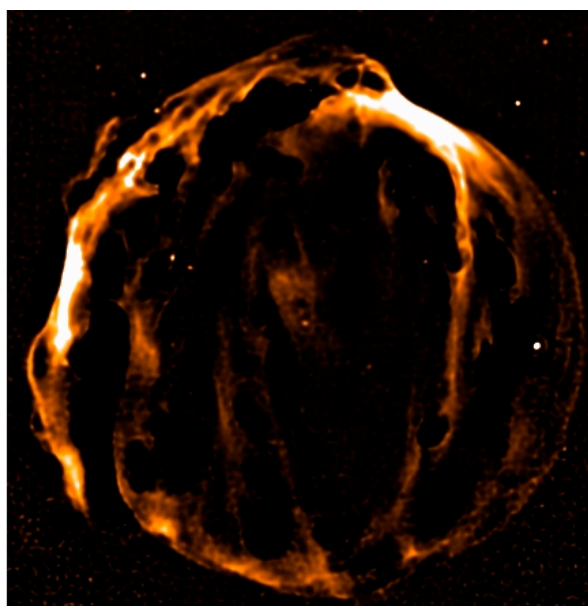
# Tycho's Supernova Remnant



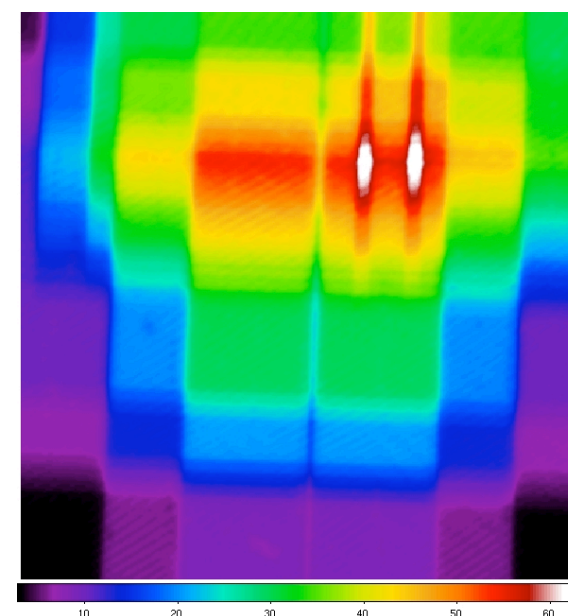
*Spitzer-MIPS 24  $\mu\text{m}$*



Co-add (1<sup>st</sup> MCM iteration)



HiRes: 40 MCM iterations



5 65  
depth-of-coverage map

FWHM of effective PRF: went from  $\sim 5.8''$  (native) to  $\sim 1.9''$

$\Rightarrow$   $\times 3$  gain in resolution per axis

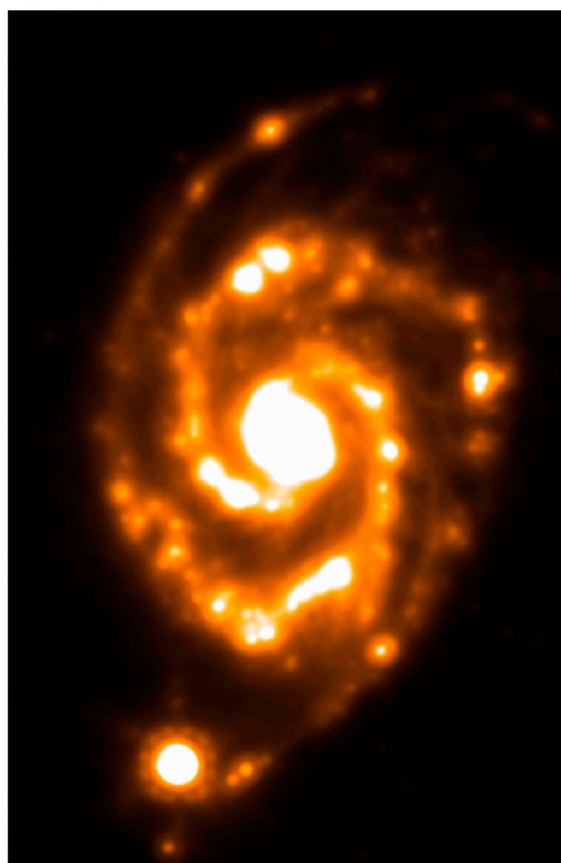


# M51 or NGC 5194/95

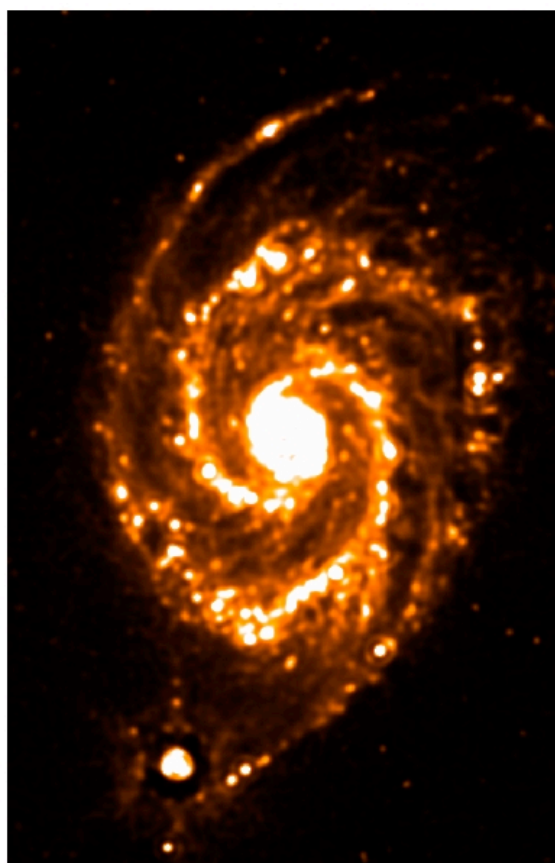


“Whirlpool Galaxy”

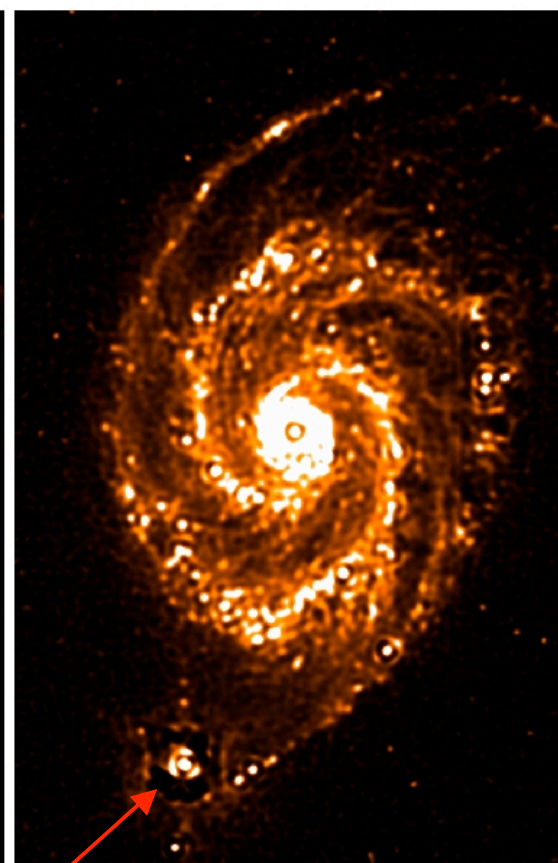
*Spitzer*-MIPS 24  $\mu\text{m}$



Co-add (1<sup>st</sup> iteration)



HiRes: 10 iterations



HiRes: 40 iterations

profile saturated!



# Digital Photo Experiment (blurred original)

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# Digital Photo Experiment “AWAIC’end”



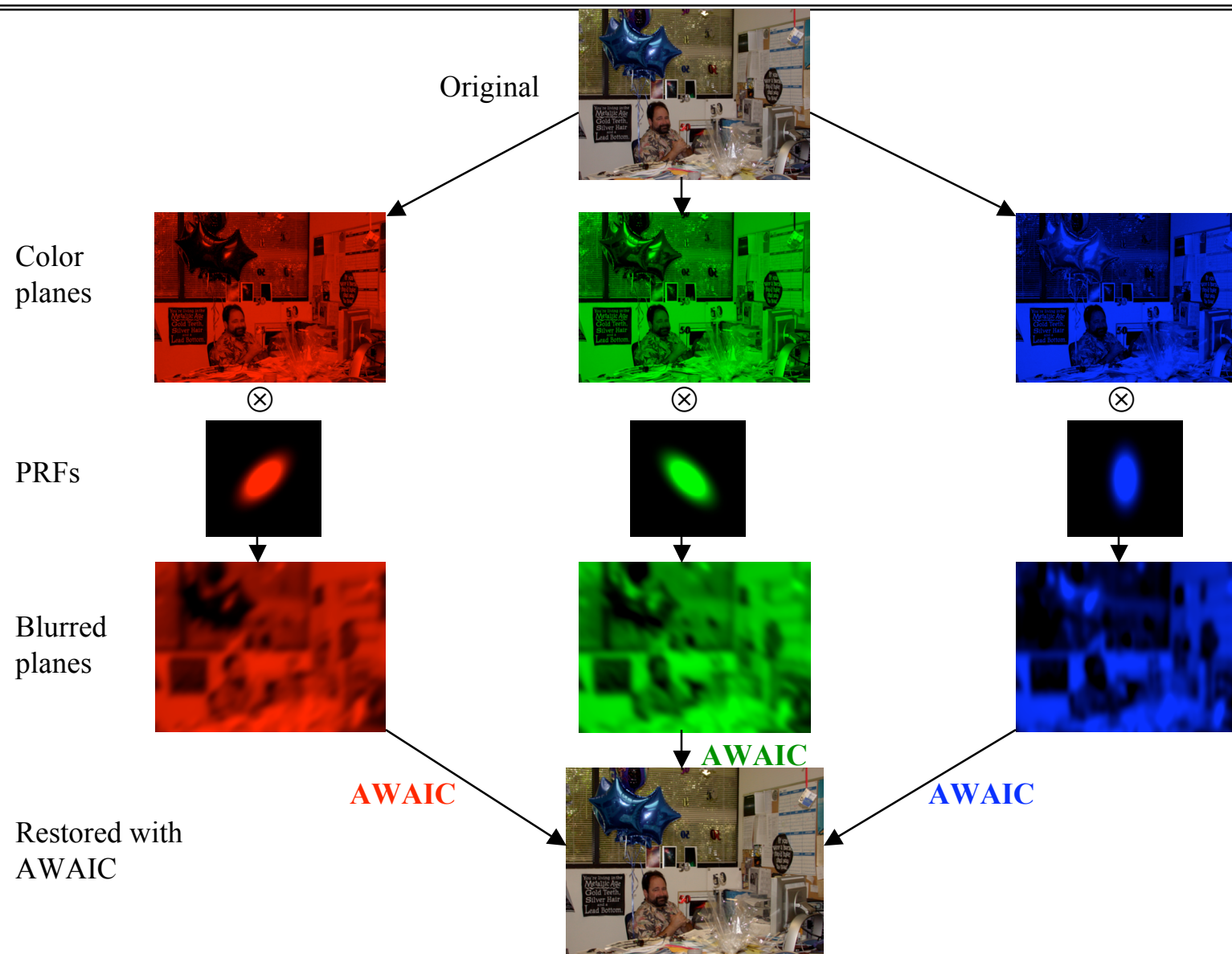


# Digital Photo Experiment (Original)





# Digital Photo Experiment





# Summary and Future Plans



- Described co-addition framework for WISE with extension to resolution enhancement
  - provides a generic tool for use on any image data that conforms with FITS/WCS standards
  - co-add products are optimized for source detection
  - bonus over previous co-adders: HiRes'ing with flux uncertainties and QA metrics for validation thereof
- Currently, AWAIC is a suite of modules implemented in ANSI C and wrapped into a Perl script
  - runs under Linux in WISE processing environment. Plan to make portable for community.
- Extend to handle time dependent PSFs (e.g., adapted to seeing) - time domain applications, e.g., LSST
- Research in progress: performance of MCM on confusion limited observations. How far below the native confusion limit can we go and reliably detect sources?
- More examples, papers, and an explanation of algorithms can be found at:  
<http://web.ipac.caltech.edu/staff/fmasci/home/wise/awaic.html>